

1. Consider the transformation: $T: P_n \rightarrow P_{n+2}$ defined by $T(p(x)) = x^2 p(x)$.

Is T a linear transformation? Prove that your answer is correct.

$$\textcircled{1} T[p(x) + q(x)] = x^2 [p(x) + q(x)] = x^2 p(x) + x^2 q(x) = T[p(x)] + T[q(x)]$$

$$\textcircled{2} T[cp(x)] = x^2 \cdot cp(x) = c \cdot x^2 p(x) = c \cdot T[p(x)]$$

$$\text{So } \boxed{\text{Yes}}$$

2. Consider the linear transformation $T: R^3 \rightarrow R^3$ where $T(\vec{x}) = A\vec{x}$. Find the kernel of this transformation given that

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 6 & 9 & 12 \end{bmatrix}$$

Find \vec{x} such that $T(\vec{x}) = A\vec{x} = \vec{0}$!

$$\left[\begin{array}{ccc|c} 1 & 2 & 3 & 0 \\ 4 & 5 & 6 & 0 \\ 6 & 9 & 12 & 0 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \begin{array}{l} x_1 = x_3 \\ x_2 = -2x_3 \\ x_3 = x_3 \end{array}$$

$$\vec{x} = \begin{bmatrix} t \\ -2t \\ t \end{bmatrix}$$

3. Is the matrix $A = \begin{bmatrix} 5 & 2 & 4 \\ 0 & 3 & 1 \\ 0 & 0 & 3 \end{bmatrix}$ diagonalizable? Explain.

$$\lambda = 3 \text{ (mult. 2)}, \lambda = 5$$

$$\lambda = 3: (\lambda I - A)\vec{x} = \vec{0} \Rightarrow \left[\begin{array}{ccc|c} -2 & -2 & -4 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \rightarrow \begin{array}{l} x_3 = 0 \\ -2x_1 - 2x_2 = 0 \\ x_1 = -x_2 \end{array} \quad \vec{x} = \begin{bmatrix} -t \\ t \\ 0 \end{bmatrix}$$

No since only one e. vector for $\lambda = 3$ w/ mult. 2 (eigen vector)

4. For $\begin{bmatrix} 3 & 10 \\ 6 & -1 \end{bmatrix}$, find all eigenvalues and bases for the corresponding eigenspaces.

$$\begin{vmatrix} \lambda-3 & -10 \\ -6 & \lambda+1 \end{vmatrix} = 0 \Rightarrow \lambda^2 - 2\lambda - 63 = 0 \quad \lambda = 9, -7$$

$$(\lambda-9)(\lambda+7) = 0 \quad \text{let } t=3$$

$$\lambda=9 \quad \left[\begin{array}{cc|c} 6 & -10 & 0 \\ -6 & 10 & 0 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 6 & -10 & 0 \\ 0 & 0 & 0 \end{array} \right] \rightarrow \vec{x} = \begin{bmatrix} \frac{5}{3}t \\ t \end{bmatrix} \rightarrow \left\{ \begin{bmatrix} 5 \\ 3 \end{bmatrix} \right\}$$

$$\lambda=-7 \quad \left[\begin{array}{cc|c} -10 & -10 & 0 \\ -6 & -6 & 0 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right] \rightarrow \vec{x} = \begin{bmatrix} -t \\ t \end{bmatrix} \rightarrow \left\{ \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\}$$

5. Use your answer from problem 4 to solve the system $\vec{Y}' = A\vec{Y}$, where A is the matrix in problem 4.

$$\vec{Y} = c_1 \begin{bmatrix} 5 \\ 3 \end{bmatrix} e^{9t} + c_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^{-7t}$$

6. Suppose 3x3 matrix A has eigenvalues $\lambda = 5$ (multiplicity two) and $\lambda = -7$, with

$$\left\{ \begin{bmatrix} 1 \\ 6 \\ 7 \end{bmatrix}, \begin{bmatrix} 1 \\ 6 \\ 0 \end{bmatrix} \right\} \text{ a basis for } E_5, \text{ and with } \left\{ \begin{bmatrix} 2 \\ 2 \\ 1 \end{bmatrix} \right\} \text{ a basis for } E_{-7}. \text{ Find the matrix P that you}$$

would use to diagonalize A, and also find D such that $D = P^{-1}AP$.

$$P = \begin{bmatrix} 1 & 1 & 2 \\ 6 & 6 & 2 \\ 7 & 0 & 1 \end{bmatrix}, \quad D = \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & -7 \end{bmatrix}$$

7. Is it possible for $\vec{Y} = c_1 \begin{bmatrix} 12 \\ 9 \end{bmatrix} e^{8x} + c_2 \begin{bmatrix} 4 \\ 3 \end{bmatrix} e^{8x}$ to be the general solution to a second order system of first order HLDE's? Explain.

No since $\vec{Y}_1 = 3\vec{Y}_2$ so \vec{Y}_1 and \vec{Y}_2 are not L.I.

8. Solve: $y_1' = 3y_1 - 18y_2$
 $y_2' = 2y_1 - 9y_2$ $A = \begin{bmatrix} 3 & -18 \\ 2 & -9 \end{bmatrix}$ $\begin{vmatrix} \lambda - 3 & 18 \\ -2 & \lambda + 9 \end{vmatrix} = 0 \Rightarrow \lambda^2 + 6\lambda + 9 = 0$
 $\lambda = -3$ (repeated)

$$\begin{bmatrix} -6 & 18 & | & 0 \\ -2 & 6 & | & 0 \end{bmatrix} \rightarrow \begin{bmatrix} -1 & 3 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \rightarrow \vec{k} = \begin{bmatrix} 3t \\ t \end{bmatrix}, \text{ use } \vec{k} = \begin{bmatrix} 3 \\ 1 \end{bmatrix} \leftarrow t=1$$

$$(A - \lambda I)\vec{p} = \vec{k} : \begin{bmatrix} -6 & -18 & | & 3 \\ 2 & -6 & | & 1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & -3 & | & \frac{1}{2} \\ 0 & 0 & | & 0 \end{bmatrix} \rightarrow \vec{p} = \begin{bmatrix} 3t + \frac{1}{2} \\ t \end{bmatrix} \text{ use } \vec{p} = \begin{bmatrix} \frac{1}{2} \\ 0 \end{bmatrix} \leftarrow t=0$$

$$\vec{Y} = c_1 \begin{bmatrix} 3 \\ 1 \end{bmatrix} e^{-3t} + c_2 \left(\begin{bmatrix} 3 \\ 1 \end{bmatrix} t e^{-3t} + \begin{bmatrix} \frac{1}{2} \\ 0 \end{bmatrix} e^{-3t} \right)$$

9. Consider the system: $y_1' = 3y_1 - 18y_2 - 7x$
 $y_2' = 2y_1 - 9y_2 + 5e^x$. Using your answer to problem 8 as a reference, find the Matrix M and vector \vec{G} that you would use to solve the system.

$$M = \begin{bmatrix} 3e^{-3t} & 3te^{-3t} + \frac{1}{2}e^{-3t} \\ e^{-3t} & te^{-3t} \end{bmatrix} \quad \vec{G} = \begin{bmatrix} -7x \\ 5e^x \end{bmatrix}$$

10. Consider the linear transformation $T: P_1 \rightarrow P_1$ where $T(ax+b) = ax + 4a - 2b$.
Find the eigenvalues and bases for the eigenspaces of this linear transformation, using $A = [T]_{\alpha}^{\alpha}$ where α is the standard basis for $P_1: \alpha = \{x, 1\}$.

$$T(x) = T(1 \cdot x + 0) = 1 \cdot x + 4 \cdot 1 - 2 \cdot 0 = 1 \cdot x + 4 \cdot 1$$

$$T(1) = T(0 \cdot x + 1 \cdot 1) = 0 \cdot x + 4 \cdot 0 - 2 \cdot 1 = 0 \cdot x - 2 \cdot 1 \rightarrow A = \begin{bmatrix} 1 & 0 \\ 4 & -2 \end{bmatrix}$$

$$|\lambda I - A| = 0 \Rightarrow \begin{vmatrix} \lambda - 1 & 0 \\ -4 & \lambda + 2 \end{vmatrix} = 0 \Rightarrow \lambda^2 + \lambda - 2 = 0 \Rightarrow \lambda = -2, 1$$

$$\lambda = -2: \begin{bmatrix} -3 & 0 & | & 0 \\ -4 & 0 & | & 0 \end{bmatrix} \rightarrow \vec{p}_1 = \begin{bmatrix} 0 \\ t \end{bmatrix} \rightarrow \text{use } t=1 \rightarrow \vec{p}_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \text{ so } 0 \cdot x + 1 \cdot 1 = \boxed{1}$$

$$\lambda = 1: \begin{bmatrix} 0 & 0 & | & 0 \\ -4 & 3 & | & 0 \end{bmatrix} \rightarrow \vec{p}_2 = \begin{bmatrix} 3 \\ t \end{bmatrix} \rightarrow \text{use } t=4 \rightarrow \vec{p}_2 = \begin{bmatrix} 3 \\ 4 \end{bmatrix} \text{ so } 3 \cdot x + 4 \cdot 1 = \boxed{3x+4}$$

i.e. $T(1) = -2(1)$

$$T(3x+4) = 1 \cdot (3x+4)$$

Scores	
9	96
8	546
7	4403876
6	56370324
5	7
4	7

11. Find one eigenvalue and one corresponding eigenvector of the linear transformation $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ where $T(x,y)$ consists of the reflection of the point (x,y) across the origin. Hint: you can use the definition $T(\vec{v}) = \lambda \vec{v}$ and just think graphically.

Any point reflective across origin will have the opposite signs

i.e. $T(x,y) = (-x, -y) = -1(x,y)$

So: $\lambda = -1$ with $\vec{v} = \langle x, y \rangle$